

Vector algebra facts sheet.

Notation

1. Vectors will be denoted by bold letters:

$$\mathbf{a}, \mathbf{b}, \mathbf{v}$$

When hand-written, vectors will be denoted with small arrows above the letters:

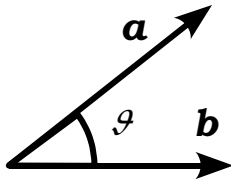
$$\vec{a}, \vec{b}, \vec{c}$$

2. Normal typeface letter will indicate a length of a vector:

$$a = |\mathbf{a}|$$

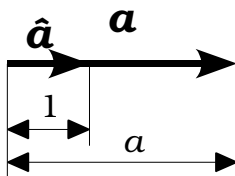
3. An angle between two vectors:

$$\vartheta = \widehat{\mathbf{a}\mathbf{b}}$$



4. A vector with a “hat” is a unit-length vector pointing in the direction of the original vector:

$$\hat{\mathbf{v}} \parallel \mathbf{v}, |\hat{\mathbf{v}}| \equiv 1, \mathbf{v} \cdot \hat{\mathbf{v}} \geq 0$$



Vector space

1. A set of all vectors forms a vector space V ; vectors can be added, for any vector there exists an opposite vector, and there exists a zero vector:

$$\forall \mathbf{a}, \mathbf{b} \in V: \mathbf{c} = \mathbf{a} + \mathbf{b} \in V$$

$$\exists \mathbf{0} \in V: \forall \mathbf{a} + \mathbf{0} = \mathbf{0} + \mathbf{a} = \mathbf{a}$$

$$\forall \mathbf{a} \in V: \exists (-\mathbf{a}) \in V:$$

$$\mathbf{a} + (-\mathbf{a}) = (-\mathbf{a}) + \mathbf{a} = \mathbf{0}$$

2. Vector addition is commutative:

$$\mathbf{a} + \mathbf{b} = \mathbf{b} + \mathbf{a} \quad (\forall \mathbf{a}, \mathbf{b} \in V)$$

3. Vectors from the vector space multiplied by numbers:

$$\forall \lambda \in \mathbb{C}: \forall \mathbf{v} \in V: \exists (\lambda \mathbf{v}): (\lambda \mathbf{v}) \in V$$

4. The following vector algebra rules hold (λ and μ are numbers):

$$\lambda(\mathbf{a} + \mathbf{b}) = \lambda \mathbf{a} + \lambda \mathbf{b}$$

$$(\lambda + \mu) \mathbf{a} = \lambda \mathbf{a} + \mu \mathbf{a}$$

$$0 \cdot \mathbf{a} = \mathbf{0} \quad (\text{zero vector})$$

Basis

1. Three non-coplanar vectors form a basis:

$$\hat{\mathbf{x}} = \mathbf{e}_1, \hat{\mathbf{y}} = \mathbf{e}_2, \hat{\mathbf{z}} = \mathbf{e}_3:$$

$$\forall i \neq j: \neg(\mathbf{e}_i \parallel \mathbf{e}_j)$$

2. Any vector can be expressed via the base vectors:

$$\mathbf{v} = v_x \hat{\mathbf{x}} + v_y \hat{\mathbf{y}} + v_z \hat{\mathbf{z}}$$

3. Vector can be defined through its components:

$$\mathbf{v} = (v_x, v_y, v_z)$$

5. Vector length can be expressed through its components (in an orthonormal basis):

$$v = |\mathbf{v}| = \sqrt{v_x^2 + v_y^2 + v_z^2}$$

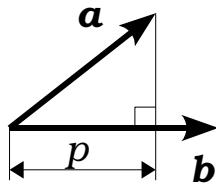
Scalar and vector products

1. Scalar product is a scalar quantity:

$$\mathbf{a} \cdot \mathbf{b} = a b \cos \widehat{\mathbf{a}\mathbf{b}}$$

2. Projection of vector \mathbf{a} into direction of vector \mathbf{b} can be expressed via the scalar product:

$$p = \frac{\mathbf{a} \cdot \mathbf{b}}{b} = a \hat{\mathbf{b}} = a \cos \widehat{\mathbf{a} \mathbf{b}}$$



3. Scalar product is commutative:

$$\mathbf{a} \cdot \mathbf{b} = \mathbf{b} \cdot \mathbf{a}$$

4. Other scalar product properties:

$$(\mathbf{a} + \mathbf{b}) \cdot \mathbf{c} = \mathbf{a} \cdot \mathbf{c} + \mathbf{b} \cdot \mathbf{c}$$

$$\lambda (\mathbf{a} \cdot \mathbf{b}) = (\lambda \mathbf{a}) \cdot \mathbf{b}$$

$$(\mathbf{a} \cdot \mathbf{a}) = a^2$$

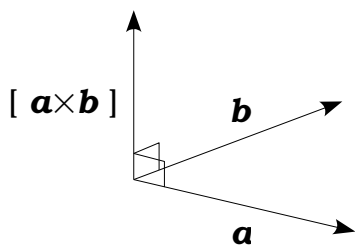
5. Scalar product in orthonormal coordinates:

$$\mathbf{a} \cdot \mathbf{b} = a_x b_x + a_y b_y + a_z b_z$$

Vector product

1. Vector product is a vector perpendicular to both multiplicands:

$$\begin{aligned} \|\mathbf{a} \times \mathbf{b}\| &= ab \sin \widehat{\mathbf{a} \mathbf{b}} \\ [\mathbf{a} \times \mathbf{b}] &\perp \mathbf{a}, \quad [\mathbf{a} \times \mathbf{b}] \perp \mathbf{b} \end{aligned}$$



2. Vector product can be calculated from the coordinates using the following determinant:

$$[\mathbf{a} \times \mathbf{b}] = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$

3. Vectors \mathbf{a} , \mathbf{b} , and \mathbf{c} form a right-handed system.

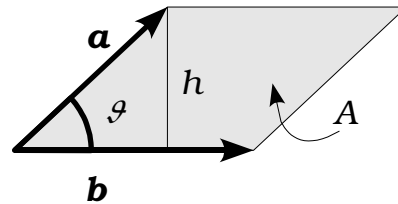
4. Vector product is anticommutative:

$$[\mathbf{a} \times \mathbf{b}] = -[\mathbf{b} \times \mathbf{a}]$$

5. Vector product gives an area of parallelepiped spanned by vectors \mathbf{a} and \mathbf{b} :

$$A = hb = ab \sin \widehat{\mathbf{a} \mathbf{b}}$$

$$h = a \sin \widehat{\mathbf{a} \mathbf{b}} = a \sin \vartheta$$



Triple product

1. Triple product of three vectors is defined via scalar and vector products:

$$(\mathbf{a}, \mathbf{b}, \mathbf{c}) \equiv (\mathbf{a} \cdot [\mathbf{c} \times \mathbf{d}])$$

2. Triple product can be "rotated":

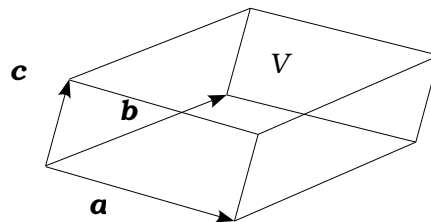
$$(\mathbf{a}, \mathbf{b}, \mathbf{c}) = (\mathbf{b}, \mathbf{c}, \mathbf{a}) = (\mathbf{c}, \mathbf{a}, \mathbf{b})$$

3. Triple product changes its sign when any two multiplicands are transposed:

$$(\mathbf{a}, \mathbf{b}, \mathbf{c}) = -(\mathbf{b}, \mathbf{a}, \mathbf{c}) = -(\mathbf{a}, \mathbf{c}, \mathbf{b})$$

4. Triple product gives a volume of a prism spanned by the three vectors:

$$V = (\mathbf{a}, \mathbf{b}, \mathbf{c})$$



Double vector product

1. The following formula holds:

$$[\mathbf{a} \times [\mathbf{b} \times \mathbf{c}]] = \mathbf{b}(\mathbf{a} \cdot \mathbf{c}) - \mathbf{c}(\mathbf{a} \cdot \mathbf{b})$$